

# BMC Helix Control-M: Fundamentals Operating

**ABSTRACT**Course Code: **AUTO-HLFO-2024****Modality**

Instructor-Led Training (ILT)

**Duration**

1 Day

**Applicable Versions**BMC Helix Control-M  
9.0.21.300**Target Audience**

- Operators

## Course Overview

The Helix Control-M is a workload automation solution that enables you to automate and schedule your business workflows across various platforms. It helps you to control various processes, called jobs, in an automatic and organized way.

This instructor-led training introduces its participants to the concepts of Helix Control-M, monitors your business workflows, and defines job workflow.

## Recommended Trainings

- Helix Control-M: Fundamentals Concepts (WBT)

## Learning Objectives

- Explain the features of Helix Control-M
- Explain Control-M Roles and their responsibilities
- Navigate the Planning, Monitoring, and Configuring domains
- Explain the New Day Process (NDP)
- Perform the steps to create a Viewpoint and Historical Viewpoint
- Perform the job search in the Monitoring domain and within a Viewpoint or Service.
- Use the Neighborhood feature to find neighborhood jobs
- Access active job details from the Monitoring domain
- Perform different job actions from the Monitoring domain
- Run jobs manually
- Manage alerts
- List the job prerequisites and where to view and amend them
- Describe the purpose and use of:
  - Lock Resources
  - Resource Pools
  - Workload Policies
- Specify an order of precedence for jobs and folders

## Course Modules

### Module 1: Control-M Concepts

- Control-M Concepts
- Control-M Roles and Responsibilities

### Module 2: Viewpoints

- Control-M Interface
- Historical Viewpoint
- Historical Viewpoint

### Module 3: Services

- Service Management

### Module 4: Job Details and Actions

- Finding Jobs
- Neighborhood Jobs
- Accessing Job Details
- Performing Job Actions

### Module 5: Alerts

- Alerts

### Module 6: Resources

- Job Prerequisites
- Lock Resources
- Resource Pools
- Precedence
- Workload Policies